

# Lecture 3

## Brief Review of Topology and Geometry I -- Topological Numbers & Differential Forms

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(March 13, 2020)

Prologue:

Paradigms in Condensed Matter Physics

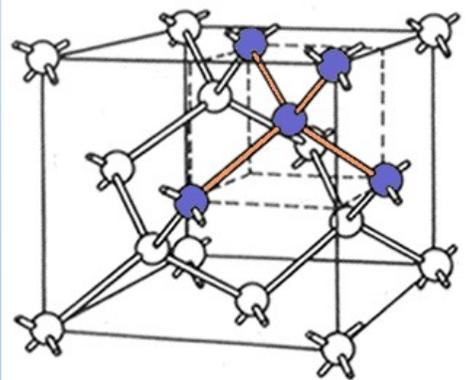
# The Search for New States/Phases of Matter

The search for **new elements** led to a golden age of **chemistry**.

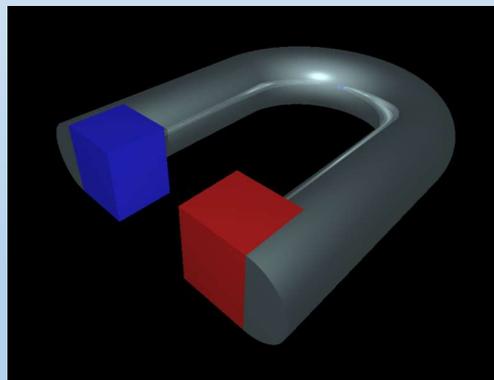
The search for **new particles** led to the golden age of **particle physics**.

Now in a **golden age** of **condensed matter physics**, we ask:  
**what are the possible fundamental states of matter?**

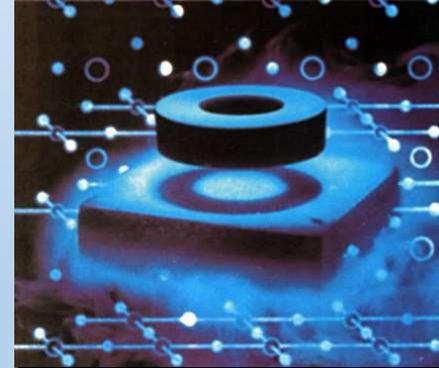
(Known in  
early 20<sup>th</sup>  
century )



Crystal: Broken  
translational symmetry



Magnet: Broken  
rotational symmetry



Superconductor: Broken  
gauge symmetry

# Landau-Ginzburg-Wilson Paradigm (CMT)

- **Classical Phase Transitions:**
  - ✓ Associated with **symmetry breaking**
  - ✓ Characterized by **local order parameter(s)**
  - ✓ Disorder-Order Transition **driven by thermal fluctuations**  
Examples: superfluids, ferromagnetism, superconductivity
- **Landau-Fermi Liquid Theory:**
  - ✓ Quasi-particles are **fermions** (existence of **Fermi surface**)
  - ✓ Quasiparticles have **same charge and spin (quantum numbers)** as electrons
  - ✓ Electron interactions incorporated in **energy as functional of quasiparticle occupation number** (quasiparticle energy and Landau parameters)  
Examples: Helium 3, many metals etc
- **Common Feature: Can be understood by Renormalization Group Flow Fixed Points (Wilson & Shankar)**

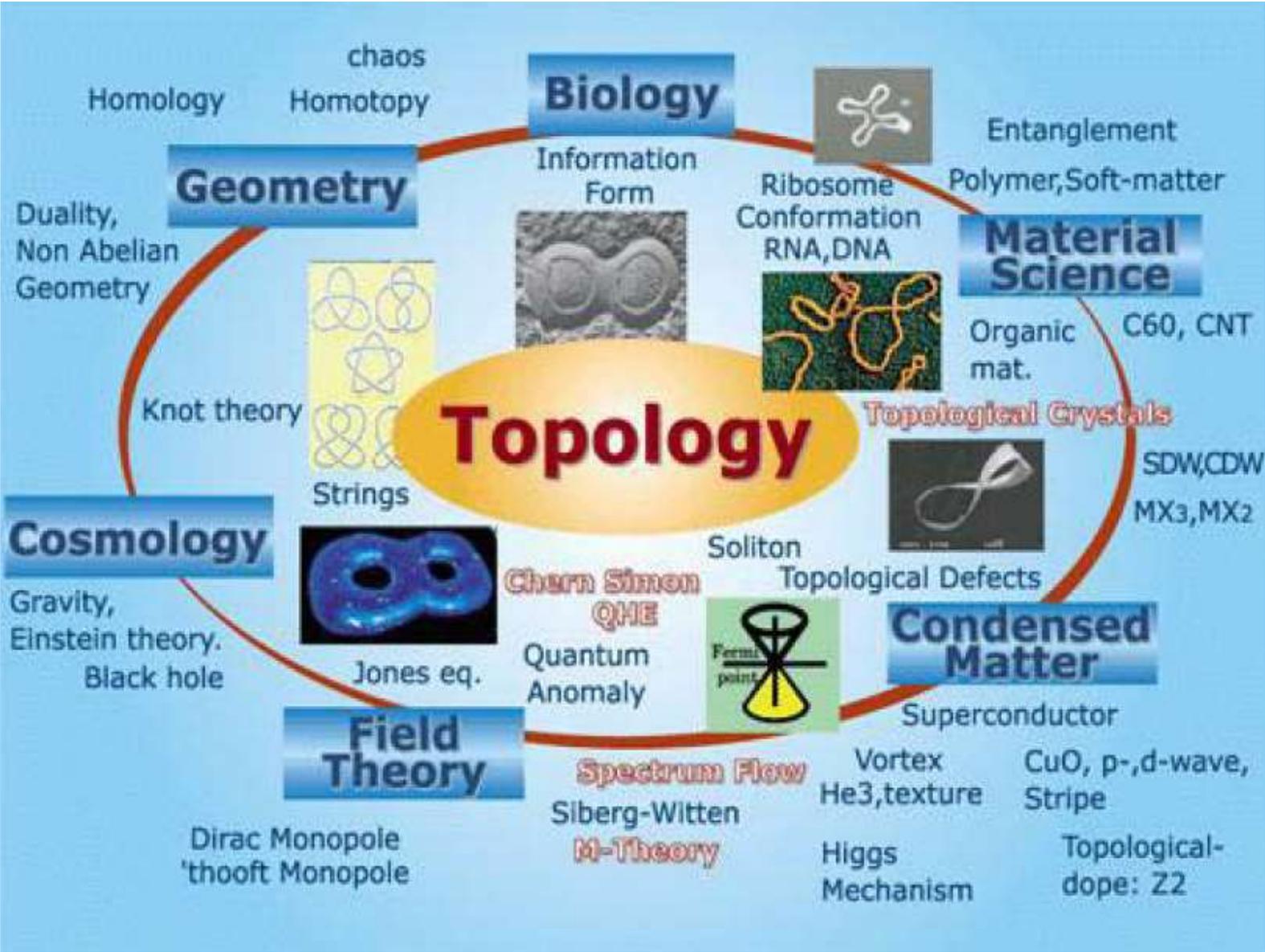
## Topological Order: Beyond the Landau Paradigm

- **Novel phases at  $T=0$  due to quantum effects (quantum matter)**
- **No symmetry breaking, no local order parameter(s)**
- **Characterized by a topological number**
- **Robust against weak disorders and interactions**
- **Correspondence between bulk and edge (in 2d) /surface (in 3d)**
- **Topology-dependent ground state degeneracy**
- **Fractionalization of quantum numbers (of quasiparticles)**
- **Fractional (exchange and exclusion) statistics of quasiparticles**
- **Intricate interplay between symmetries and topological orders**
  
- **Examples: quantum Hall effect, Mott insulators, quantum spin Hall effect, quantum spin liquids, topological insulators/superconductors, Dirac/Weyl semi-metals, connection w/ fundamental Physics etc**

# Respondence to Professor Wen's Classes

- Class 1: Symmetry Breaking in  $T=0$  Quantum Phase Transition  
(with the example of the 1d Transverse Ising Model)
  
- Class 2: Topological Order (beyond Landau's paradigm)  
(in the context of String-Net Models)

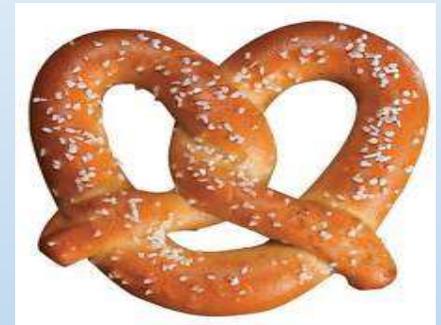
# A Primer of Topology



# Surface of Orange, Mug and Pretzel



# Surface of Orange, Mug and Pretzel



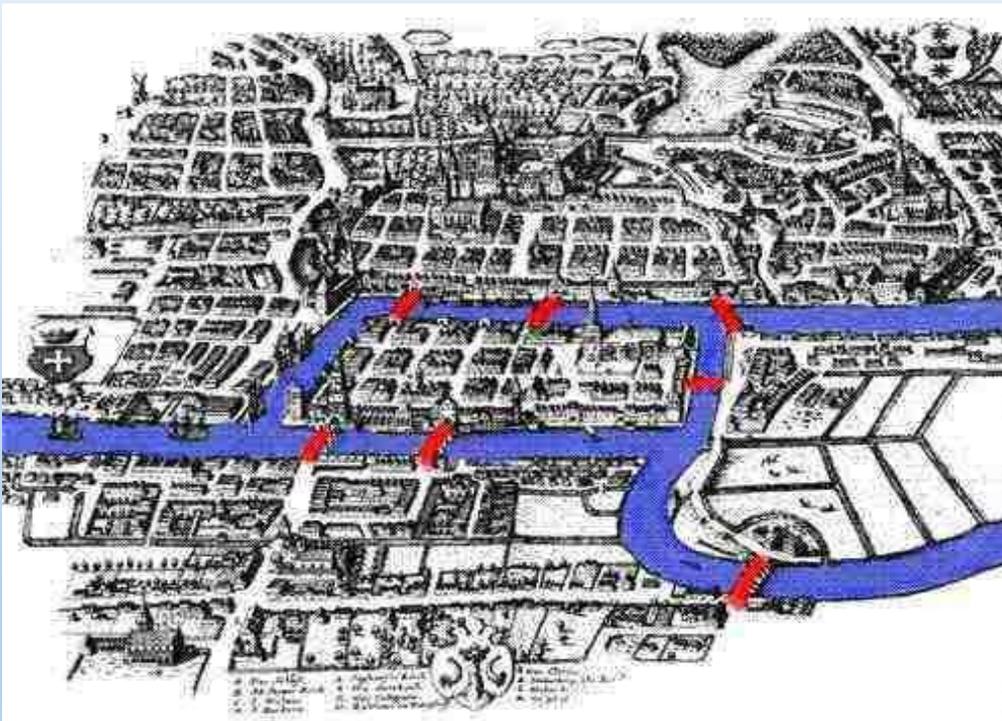
Topology: Properties unchanged under continuous deformations

# Surface of Orange, Mug and Pretzel



How to describe and characterize topological differences between these three things?

# Königsberg Seven Bridge Problem



**Problem:**

**Is it possible for a walker to go through all several bridges only once and to return to the starting position?**

[source: [MacTutor History of Mathematics Archive](#)]

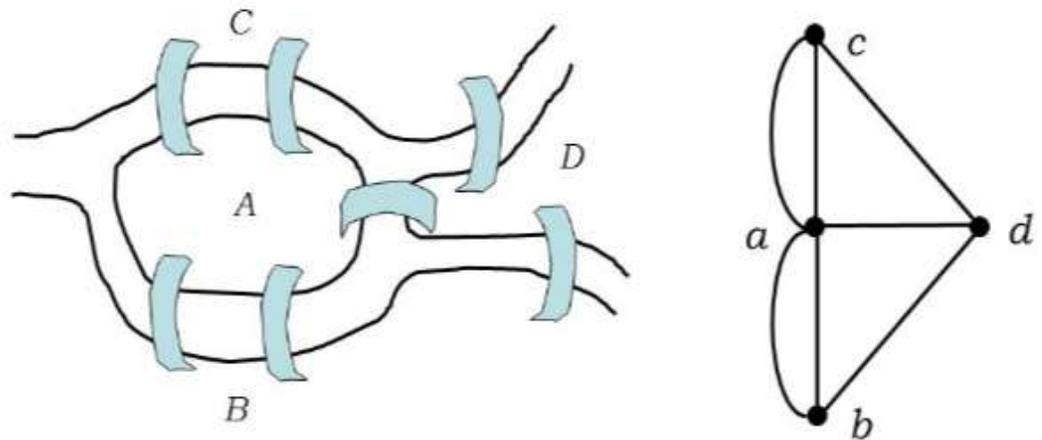
# Euler's Solution of the Seven Bridge Problem



Switzerland Stamp (2207)

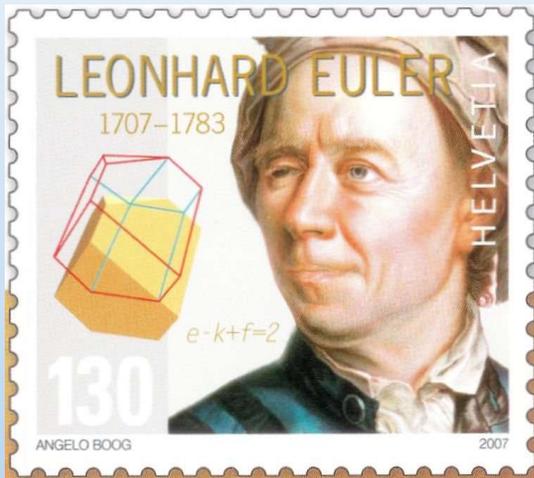
Impossible! Because each vertex is connected to an **odd number** of links.

- The Seven bridges of Königsberg



Credit: Aiden Ball

# Euler Characteristics for Polyhedra



Name	Image	Vertices $V$	Edges $E$	Faces $F$	Euler characteristic: $V - E + F$
Tetrahedron		4	6	4	2
Hexahedron or cube		8	12	6	2
Octahedron	$\equiv$ 	6	12	8	2
Dodecahedron		20	30	12	2
Icosahedron		12	30	20	2

(Credit: Wikipedia)

$$\chi(M) \equiv V - E + F \quad (M: \text{2d closed surface})$$

Actually true for any **Convex/Spherical polyhedra!**



# Gauss-Bonnet Theorem

$$\frac{1}{2\pi} \int_M K dA = \chi(M) = 2(1 - g).$$

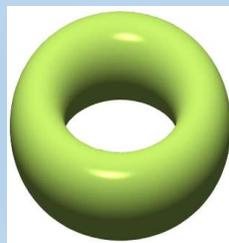
where

M: 2d closed surface

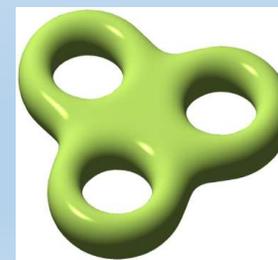
K: Gauss Curvature ,  $g$ : genus (# handles)



$$g = 0$$



$$g = 1$$



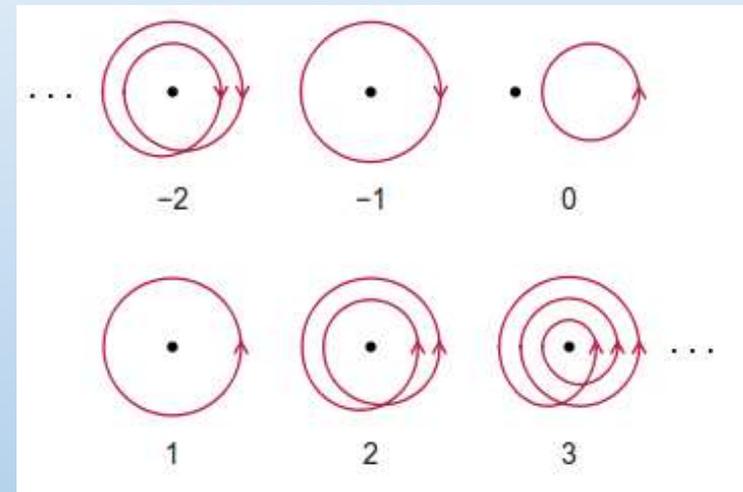
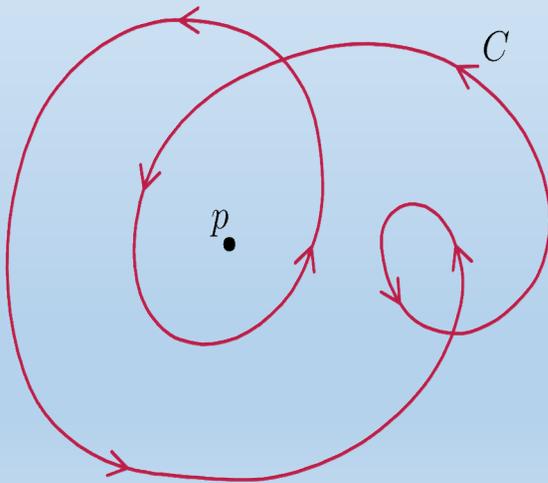
$$g = 3$$

## Ideas inspired by this Line of Thoughts

- Discrete approach can be Exact for Topology of a Continuous Object  
(Combinatoric Topology)
  - Bulk-Boundary Relationship plays a Central role in Topology  
(Homology)
  - Topological Inumber/nvariant can be expressed as an Integral  
(Differential Topology: Cohomology and Homotopy)
- Integral Calculus is Important in Curved Manifold without Metric

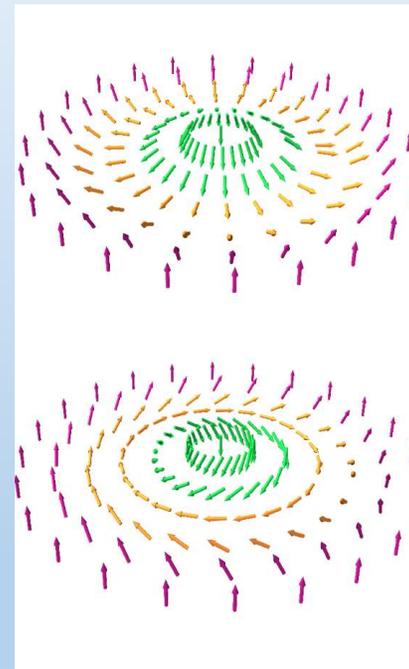
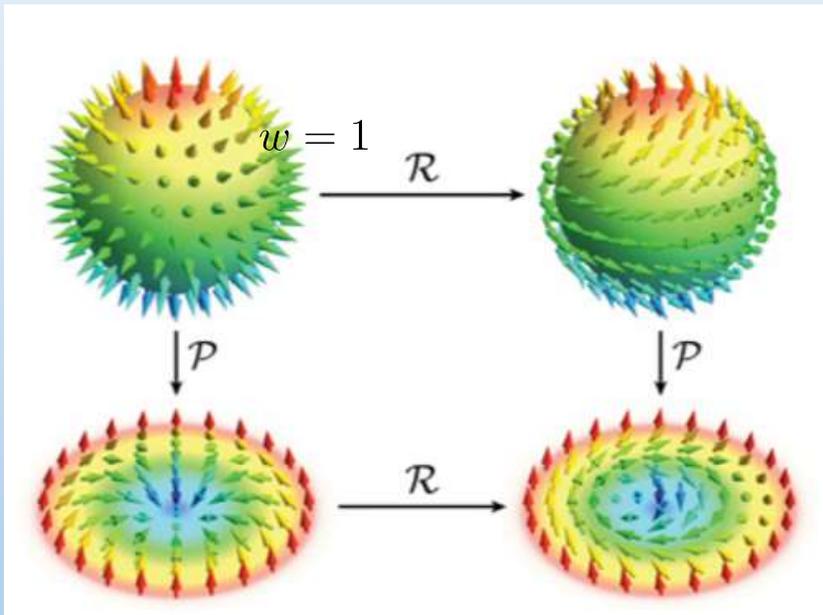
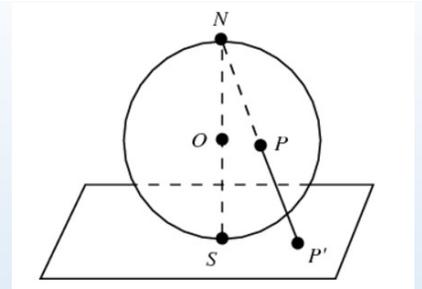
# Winding Numbers I ( $S^1 \rightarrow S^1$ )

Contour integral in  
complex analysis

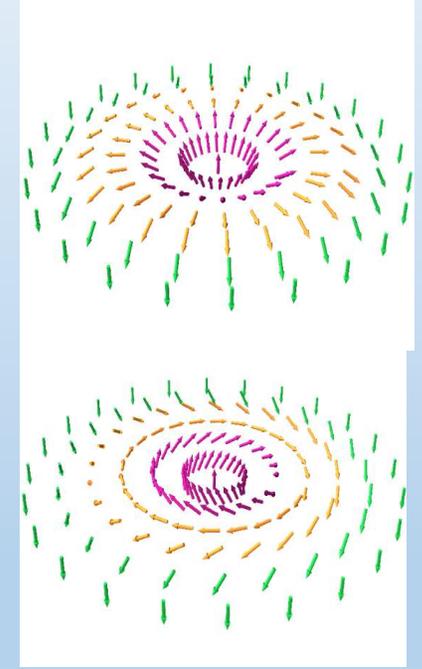


$$w = \frac{1}{2\pi} \int_0^{2\pi} d\theta \frac{d\theta'}{d\theta} = \text{integer}$$

# Winding Number II ( $S^2 \rightarrow S^2$ )



$$w = 1$$



$$w = -1$$

$$w = \frac{1}{4\pi} \int dx dy \mathbf{n} \cdot \left( \frac{\partial \mathbf{n}}{\partial x} \times \frac{\partial \mathbf{n}}{\partial y} \right)$$

# A Primer of Topology for Physicists

- Manifold and Differential Forms  
Stokes Theorem
- Mapping Degree/Winding Numbers  
Kronecker Invariant, WZW Action
- Topology in Gauge Theory  
Aharonov-Bohm Effect and Flux Quantum  
Dirac Quantization for Magnetic Monopole  
Instantons and Theta Vacuum  
Index Theorem for Zero Modes and Anomaly
- Descent Equations:  
Relations in Different Dimensions

# Topology

Definition: Properties that remain unchanged under continuous (or smooth) deformation.

1. Combinatoric Topology: Pure Math

2. Algebraic Topology:

(1) Homotopy group, (2) Homology group, (3) Cohomology group

3. Differential Topology:

Differential forms  $\Rightarrow$  Integral topological invariants  $\Rightarrow$  Topological number

In physics we need to get a number to be compared with experiments, so topological numbers obtained by integral invariants are very useful in physics, though not every topological number can be expressed as an integral.

## Integration over a smooth manifold

Manifolds are generalization of curves, surfaces, hyper-surfaces, etc.

A manifold (with dimension  $n$ ) is defined by the following data:

1. Local coordinates patches (with  $n$  coordinates in each patch)

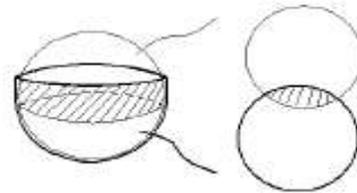


Fig: local coordinates for a 2-sphere

2. In overlapping region(s), the coordinate transformations

$$x'^{\mu} = f^{\mu}(x^1, x^2, \dots, x^n), \quad (\mu = 1, 2, \dots, n)$$

must be smooth.

3. Collection of all admissible coordinates patches that covers the whole manifold, a differential structure).

Here, properties 2 and 3 contain global information.

## Integration elements

In  $\mathbb{R}^3$ , we have the following integrations.

(1) Line integral  $\int_C \vec{A} \cdot d\vec{x}$

(2) Surface integral  $\int_S \vec{E} \cdot d\vec{\sigma}$

(3) Volume integral  $\int_V f(\vec{x}) d\tau$

In higher dimensions, the surface and volume elements are not vector and scalar but anti-symmetric tensors.

$$d\vec{\sigma} \rightarrow d\sigma^{\mu\nu} = dx^\mu \wedge dx^\nu$$

$$d\tau \rightarrow d\tau^{\mu\nu\lambda} = dx^\mu \wedge dx^\nu \wedge dx^\lambda$$

Here, for example, an volume element formed by three infinitesimal non-planar vectors  $\delta u_a$  ( $a = 1, 2, 3$ ) is understood as

$$dx^\mu \wedge dx^\nu \wedge dx^\lambda \rightarrow \epsilon^{abc} (\delta u_a)^\mu (\delta u_b)^\nu (\delta u_c)^\lambda . \quad (1)$$

## Differential forms as "integrands"

The differential  $k$ -form (of degree  $k$ ) is

$$\omega = \frac{1}{k!} \omega_{\mu_1 \dots \mu_k} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_k} ;$$

where  $\omega_{\mu_1 \dots \mu_k}$  and  $dx^{\mu_1} \wedge \dots \wedge dx^{\mu_k}$  are totally anti-symmetric, respectively. We have following properties:

(1)  $dx^\mu \wedge dx^\nu = -dx^\nu \wedge dx^\mu$ . More generally,

$$\omega_1 \wedge \omega_2 = (-1)^{\deg(\omega_1) \cdot \deg(\omega_2)} \omega_2 \wedge \omega_1.$$

(2) Define:  $d\omega = \frac{1}{k!} \frac{\partial \omega_{\mu_1 \dots \mu_k}}{\partial x^\mu} dx^\mu dx^{\mu_1} \wedge \dots \wedge dx^{\mu_k}$ .

Namely we have  $d \equiv \frac{\partial}{\partial x^\mu} dx^\mu \wedge$ .

(3)  $d^2 = 0$  (Most important property)

(4) Leibniz Rule:  $d(\omega_1 \wedge \omega_2) = (d\omega_1) \wedge \omega_2 + (-1)^{\deg \omega_1} \omega_1 \wedge (d\omega_2)$

## Differential Forms (cont.)

(5) Given a map  $f : M \rightarrow N$ , ( $x^\mu \mapsto y^\mu$ ), then for a  $k$ -form  $\omega$  on  $N$  we obtain a form

$$\begin{aligned} f^*\omega &= \frac{1}{k!} \omega_{\alpha_1, \dots, \alpha_k}(y(x)) dy^{\alpha_1}(x) \wedge \dots \wedge dy^{\alpha_k}(x) \\ &= \frac{1}{k!} \omega_{\alpha_1, \dots, \alpha_k}(y(x)) \frac{\partial y^{\alpha_1}}{\partial x^{\mu_1}} \dots \frac{\partial y^{\alpha_k}}{\partial x^{\mu_k}} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_k} \end{aligned}$$

defined on  $M$ . This operation is called **Pull-Back**.

(6) Stoke's Theorem describes the Bulk-Boundary Relation:

$$\int_V d\omega = \int_{\partial V} \omega$$

Corollary: If  $\omega$  is a closed form, i.e.  $d\omega = 0$ , then  $\int_S \omega$  is unchanged under smooth deformation of the compact manifold  $S$ . (A compact manifold has no boundary.)

Therefore, a closed form is always associated with an integral topological invariant. Useful topological integral invariants include mapping degrees, or winding numbers, and Chern numbers.

## Stokes' Theorem in 3 dimensions

For 0-form  $f(\vec{x}) \equiv f(x, y, z)$ , then 1-form  $df = \frac{\partial f}{\partial x^i} dx^i$

For 1-form  $A = A_i(\vec{x}) dx^i$ , we have two possible derivations

Curl (2-form):  $dA = \frac{1}{2} \frac{\partial A_j}{\partial x^i} dx^i \wedge dx^j$ ,  $(dA)_{ij} = \epsilon_{ijk} (\nabla \times \vec{A})_k$

Dual (2-form):  $*A = \frac{1}{2} \epsilon_{ijk} A_k dx^i \wedge dx^j$ ,

Divergence (0-form):  $d * A = \frac{\partial}{\partial x^l} A_k (\frac{1}{2} \epsilon_{ijk}) dx^l \wedge dx^i \wedge dx^j$

$$*(d * A) = \epsilon_{ijl} (d * A)_{ijl} = \nabla \cdot \vec{A}$$

Stokes Theorem unifies the usual Green's, Stokes's and Gauss's Theorems:

## Mapping Degree

$\varphi : M \rightarrow N$  ( $\dim(M) = \dim(N)$ ,  $M, N$  are compact and oriented)

Intuition: The image of  $\varphi(M)$  must cover  $N$  an integer times.

Consider  $\varphi : S^1 \rightarrow S^1$

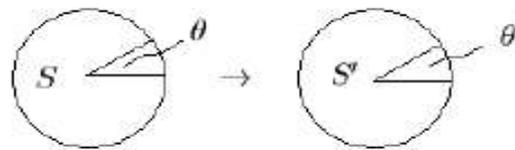


Fig: Map  $S^1 \rightarrow S^1$

(1).  $\theta \mapsto \theta' = \theta$  ( $0 \leq \theta < 2\pi$ ), it covers 1 time.

(2).  $\theta \mapsto \theta' = 2\theta$  ( $0 \leq \theta < 2\pi$ ), it covers 2 time.

(3).  $\theta \mapsto \theta' = \theta$  ( $0 \leq \theta < \pi$ )  
 $= 2\pi - \theta$  ( $\pi \leq \theta < 2\pi$ )

it covers 0 times.

The (integer) number of times that  $f(M)$  covers  $N$  can be expressed by an integral mathematically.

## Mapping degree (cont.)

Mapping degree or winding number:

$$\deg(\varphi) = \frac{\int_M \varphi^* \omega}{\int_N \omega}$$

where  $\omega$  is  $n$ -form on  $N$  (Volume form).

Example 1. **Kronecker Integral:**  $N = S^n$

$\varphi : M \rightarrow S^n$  ( $S^n$  is unit sphere ( $\sum_{\alpha=1}^{n+1} (y^\alpha)^2 = 1$ ).)

So we have  $\sum_{\alpha}^{n+1} (\varphi^\alpha(x))^2 = 1$  (unit vector in  $\mathbb{R}^{n+1}$ )

Take  $\omega =$  to be the volume element

$$\deg(\varphi) = \frac{1}{V_n} \int d^n x \frac{1}{n!} \varepsilon^{\mu_1 \dots \mu_n} \varepsilon_{\alpha_1 \dots \alpha_{n+1}} \varphi^{\alpha_1}(x) \frac{\partial \varphi^{\alpha_2}(x)}{\partial x^{\mu_1}} \dots \frac{\partial \varphi^{\alpha_{n+1}}(x)}{\partial x^{\mu_n}}$$

with  $V_n = \frac{(n+1)\pi^{\frac{n+1}{2}}}{\Gamma[\frac{1}{2}(n+3)]}$ .

## Properties of Mapping Degree

We have the following properties:

**Homotopy Invariant:**  $\deg(\varphi)$  is homotopic invariant.

**Definition:** We say  $\varphi_1 \sim \varphi_2$  if exists smooth  $F: M \times I \rightarrow N$ , such that

$$F(x, t = 0) = \varphi_1(x), \quad F(x, t = 1) = \varphi_2(x)$$

( $F$  represents the process in which  $\varphi_1$  is deformed to  $\varphi_2$ )

$$\varphi_1 \sim \varphi_2 \Rightarrow \deg(\varphi_1) = \deg(\varphi_2)$$

Note. The converse is NOT true generally, but true in Kronecker's case. We have **Hopf Theorem**. Suppose  $M$  is connected, compacted and oriented. For maps  $\varphi_1, \varphi_2: M \rightarrow S^n$ , ( $\dim(M) = n$ ). We have

$$\varphi_1 \sim \varphi_2 \Leftrightarrow \deg(\varphi_1) = \deg(\varphi_2)$$

## Homotopy Integral Invariant (cont.)

Example 2: The case when  $N = G$  (Lie Group)

Here  $\dim(M) \neq \dim(N)$  is allowed.

Consider a map  $g : M \rightarrow G$ , ( $x \mapsto g(x)$ ,  $g(x) \in G$ ). The form

$$\text{Tr}\{[g^{-1}(x)dg(x)]^k\}$$

is the pull-back on  $M$  of  $[g^{-1}dg]^k$  on  $G$ . Here  $g^{-1}dg$  is the Cartan-Maurer 1-form on  $G$ :

$$g^{-1}dg = \sum_{a=1}^r T^a V_a^a(g) dg^\alpha$$

Where  $r = \dim(G)$  and  $g^\alpha$  are coordinates on  $G$ . So the pull-back is given by

$$g^{-1}(x)dg(x) = \sum_{a=1}^r T^a \tilde{V}_\mu^a(g(x)) dx^\mu ,$$

where  $\tilde{V}_\mu^a = V_a^a(g(x)) \frac{\partial g^\alpha}{\partial x^\mu}$ .

## Homotopy Integral Invariant (cont.)

Let us define

$$w[g(x)] = c_k \int_M \text{Tr}\{[g^{-1}(x)dg(x)]^k\}.$$

**Lemma.**  $\text{Tr}(g^{-1}dg)^k = 0$ , if  $k = \text{even}$ ;  
 $d\text{Tr}(g^{-1}dg)^k = 0$ , if  $k = \text{odd}$ .

When  $M$  is a  $k$ -sphere,  $S^k$  with  $k = \text{odd}$ ,  $c_k = \frac{(\frac{k-1}{2})!}{(2\pi)^{\frac{k+1}{2}} k!}$ .

**Theorem.**  $w[g(x)] = \text{integer}$ .

Application: In gauge theories, a map  $g : M \rightarrow G$  is called a gauge transformation and  $w(g)$ , if non-zero, is called the winding number of the *large gauge transformation*  $f$ .

*Example 3:*  $M = S^3, N = SU(2)$ . In this case,  $w(g)$  can be calculated by either of the above formulas.

Let us define  $(g_1 \circ g_2)(x) = g_1(x) \cdot g_2(x)$ . Then we have the following property:

$$w(g_1 \circ g_2) = w(g_1) + w(g_2).$$

$$\text{Tr}[(g_1 g_2)^{-1} d(g_1 g_2)]^3 = \text{Tr}[(g_1^{-1} dg_1)]^3 + \text{Tr}[(g_2^{-1} dg_2)]^3 + d(\text{something}).$$

# Reference Books

1. H. Flanders, "Differential Forms with Applications to the Physical Sciences" , (Dover Publications, 1989)
2. C. Nash and S. Sen, "Topology and Geometry for Physicists", (Academic Press, Inc. , London, 1983)

These are suitable for this class. For advanced textbooks see, e.g.,

3. Y. Choquet-Bruhat, C. Dewitt-Morette and M. Dillard-Bleick, "Analysis, Manifolds and Physics" , Revised Edition, (North-Holland, Amsterdam, 1982)
4. T. Frankel, "The Geometry of Physics -- An Introduction", (Cambridge University Press, 1997)

## Problems

1. Given  $\alpha = 2yzdx + x^2dy + xyzdz$ ,  $\beta = \sin xdx + \cos ydy$ , compute (1)  $\alpha \wedge \beta$ , and (2)  $d\alpha$ .
2. Given  $\alpha$  and  $\beta$  as given above, explicitly compute (3)  $d(d\alpha)$  and (4)  $d(\alpha \wedge \beta)$ .
3. If further  $\gamma = 3z^3dx + (x^2 + y^2 + z^2)dy + 5y^2 dz$ , compute  $\alpha \wedge \beta \wedge \gamma = ?$
4. Consider a 2-sphere  $S^2$  described by  $x^2 + y^2 + z^2 = 1$ .  
Show that its surface element is given by  $\beta = xdy \wedge dz + ydz \wedge dx + zdx \wedge dy$ .  
Hint: Use the polar coordinates:  $x = \sin\theta \cos\phi$ ,  $y = \sin\theta \sin\phi$ ,  $z = \cos\theta$ .  
prove that  $\beta = \sin\theta d\theta \wedge d\phi$ ,  $d\beta = 3dx \wedge dy \wedge dz$ .

*End*